

# Remark on an Algebraic Solution of Painlevé Sixth Equation Obtained by Hitchin

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## 1 Introduction

The purpose of this paper is to study a free divisor related with an algebraic solution of Painlevé sixth equation found by Hitchin [2]. Applying M. Kato's idea, we construct an algebraic solution of Painlevé sixth equation from a holonomic system of rank two associated with a free divisor in  $\mathbf{C}^3$  defined by a weighted homogeneous polynomial.

## 2 A free divisor related with a polynomial of icosahedral coefficients

We start this note with introducing a matrix with polynomial entries

$$M = \begin{pmatrix} x_1 & 2x_2 & 4x_3 \\ -135x_1(x_1^2 + 3x_2) & -x_1^4 + 324x_1^2x_2 + 81x_2^2 + x_3 & 108(19x_1^6 + 741x_1^4x_2 - 4617x_1^2x_2^2 + 243x_2^3) \\ x_1^4 - 324x_1^2x_2 - 81x_2^2 + x_3 & -20x_1x_2(x_1^2 - 27x_2) & 8x_1(x_1^6 + 1539x_1^4x_2 + 20007x_1^2x_2^2 - 41553x_2^3) \end{pmatrix}$$

Using  $M$ , we define  $h_0 = -\frac{1}{4} \det M$ . Then  $h_0$  is regarded as a cubic polynomial of  $x_3$ :

$$h_0 = x_3^3 + \sigma_1 x_3^2 + \sigma_2 x_3 + \sigma_3,$$

where

$$\begin{aligned} \sigma_1 &= 0, \\ \sigma_2 &= -3(x_1^8 + 2052x_1^6x_2 + 40014x_1^4x_2^2 - 166212x_1^2x_2^3 + 6561x_2^4), \\ \sigma_3 &= 2(x_1^4 + 81x_2^2)(x_1^8 - 4698x_1^6x_2 - 810486x_1^4x_2^2 + 380538x_1^2x_2^3 + 6561x_2^4). \end{aligned}$$

Let  $V_1, V_2, V_3$  be vector fields defined by the matrix  $M$ , namely,

$${}^t(V_1, V_2, V_3) = M^t(\partial_{x_1}, \partial_{x_2}, \partial_{x_3}).$$

Then it is easy to see that  $V_1$  is an Euler vector field with weight  $(1, 2, 4)$  and that

$$V_1 h_0 = 12h_0, \quad V_2 h_0 = V_3 h_0 = 0.$$

Moreover

$$[V_1, V_2] = 2V_2, \quad [V_1, V_3] = 3V_3,$$

and

$$[V_2, V_3] = -16x_1(x_1^2 - 27x_2)V_2 + 81(x_1^2 + 3x_2)V_3.$$

As a consequence,  $h_0 = 0$  is a free divisor in  $\mathbf{C}^3$  in the sense of Saito [4].

The  $j$ -invariant of  $h_0$  is defined to be

$$J(\sigma_1, \sigma_2, \sigma_3) = \frac{(\sigma_1^2 - 3\sigma_2)^3}{-27(\sigma_3 - \frac{1}{3}\sigma_1\sigma_2 + \frac{2}{27}\sigma_1^3)^2 - 4(\sigma_2 - \frac{1}{3}\sigma_1^2)^3} = \frac{27\sigma_2^3}{27\sigma_3^2 + 4\sigma_2^3}.$$

Put  $m = \frac{x_2}{x_1^2}$ . Then  $J(\sigma_1, \sigma_2, \sigma_3)$  turns out to be

$$\varphi(m) = -\frac{(1 + 2052m + 40014m^2 - 166212m^3 + 6561m^4)^3}{2304m(-1 + 99m + 81m^2)^5}.$$

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**Remark 2.1** Putting  $m = \frac{z_1^5}{9z_2^5}$ , we find that  $\varphi(m)$  takes the form  $\frac{H^3}{256f^5}$ , where

$$\begin{aligned} f &= z_1 z_2 (z_1^{10} + 11z_1^5 z_2^5 - z_2^{10}), \\ H &= -(z_1^{20} + z_2^{20}) + 228(z_1^{15} z_2^5 - z_1^5 z_2^{15}) - 494z_1^{10} z_2^{10}. \end{aligned}$$

As is shown in Klein's book [3],  $f$  and  $H$  are the defining polynomial of vertices and that of centers of faces of Icosahedron, respectively. It is interesting to explain the reason why the polynomials  $f$  and  $T$  appear in the numerator and the denominator of  $\varphi(m)$ .

### 3 Solution of $J(t) = \varphi(m)$

The  $j$ -invariant of the cubic polynomial  $P_1(z) = z(z-1)(z-t)$  is known to be

$$J(t) = \frac{(1-t+t^2)^3}{t^2(1-t)^2}.$$

It is straightforward to show that

$$\begin{aligned} t &= \frac{1+2s-5s^2-5s^4-2s^5+s^6-8s^2u}{1+2s-5s^2-5s^4-2s^5+s^6+8s^2u} \\ m &= \frac{(-11+5\sqrt{5})(-2+s-\sqrt{5})(1+2s-\sqrt{5})}{18(-2+s+\sqrt{5})^2(1+2s+\sqrt{5})} \end{aligned} \quad (1)$$

give a solution of

$$J(t) = \varphi(m),$$

where  $u^2 = s(s^2 + s - 1)$ . If  $x_2 = mx_1^2$ , then

$$\begin{aligned} \sigma_2 &= -3(1+2052m+40014m^2-166212m^3+6561m^4)x_1^8, \\ \sigma_3 &= 2(1+81m^2)(1-4698m-810486m^2+380538m^3+6561m^4)x_1^{12}. \end{aligned}$$

Moreover, by substituting  $m$  with the rational function of  $s$  in (1), we find that

$$\begin{aligned} \sigma_2 &= -\frac{3 \cdot 5^4 (-25+11\sqrt{5})^2 (1+4s-6s^2-20s^3+15s^4-216s^5+236s^6+216s^7+15s^8+20s^9-6s^{10}-4s^{11}+s^{12})x_1^8}{2^2(s-2+\sqrt{5})^8(s+(1+\sqrt{5})/2)^4}, \\ \sigma_3 &= \frac{5^6(-25+11\sqrt{5})^3(1+s^2)(1+2s-6s^2-2s^3+s^4)(1-4s+6s^2+4s^3+s^4)(1+8s+20s^2+8s^3-106s^4-8s^5+20s^6-8s^7+s^8)x_1^{12}}{2^2(s-2+\sqrt{5})^{12}(s+(1+\sqrt{5})/2)^6}. \end{aligned}$$

We put  $P(z) = P_1(z + \frac{t+1}{3}) = (z + \frac{t+1}{3})(z + \frac{t-2}{3})(z + \frac{1-2t}{3})$  and introduce polynomials  $\tau_2, \tau_3$  of  $t$  by

$$P(z) = z^3 + \tau_2 z + \tau_3.$$

Clearly the equation  $P(z) = 0$  has three roots

$$\zeta_0 = \frac{-t-1}{3}, \quad \zeta_1 = \frac{2-t}{3}, \quad \zeta_2 = \frac{2t-1}{3}.$$

We regard  $t$  as a rational function of  $s$  by the relation in (1) for a moment. Then it is straightforward to show that

$$\begin{aligned} \tau_2 &= -\frac{(1+4s-6s^2-20s^3+15s^4-216s^5+236s^6+216s^7+15s^8+20s^9-6s^{10}-4s^{11}+s^{12})}{3(1+2s-5s^2-5s^4-2s^5+s^6+8s^2u)^2}, \\ \tau_3 &= \frac{2(1+s^2)(1+2s-6s^2-2s^3+s^4)(1-4s+6s^2+4s^3+s^4)(1+8s+20s^2+8s^3-106s^4-8s^5+20s^6-8s^7+s^8)}{27(1+2s-5s^2-5s^4-2s^5+s^6+8s^2u)^3}. \end{aligned}$$

Then computing the ratio  $\frac{\sigma_j}{\tau_j}$  ( $j = 2, 3$ ), we find that

$$\sigma_2 = Q(s)^2 \tau_2, \quad \sigma_3 = Q(s)^3 \tau_3,$$

where

$$Q(s) = \frac{75(-25+11\sqrt{5})(1+2s-5s^2-5s^4-2s^5+s^6+8s^2u)x_1^4}{2(s-2+\sqrt{5})^4(s+(1+\sqrt{5})/2)^2}$$

As a consequence, we find that

$$h_0 = x_3^3 + \sigma_2 x_3 + \sigma_3 = (x_3 - Q(s)\zeta_0)(x_3 - Q(s)\zeta_1)(x_3 - Q(s)\zeta_2).$$

Noting this, we put  $z_j = Q(s)\zeta_j$  ( $j = 0, 1, 2$ ). Then  $h_0 = (x_3 - z_0)(x_3 - z_1)(x_3 - z_2)$ .

## 4 Holonomic system related with the free divisor $h_0 = 0$

We introduce the following matrices to construct a holonomic system.

$$\begin{aligned} A_1 &= \begin{pmatrix} r_0 & 0 \\ 0 & 2 + r_0 \end{pmatrix} \\ A_2 &= \begin{pmatrix} 0 & 1 \\ -162\{(-107 + 72\sqrt{5})x_1^4 + 162(4 + 3\sqrt{5})x_1^2x_2 - 243x_2^2 - x_3\} & 0 \end{pmatrix} \\ A_3 &= \begin{pmatrix} 8x_1\{(-7 + 3\sqrt{5})x_1^2 + 9(1 + \sqrt{5})x_2\} & \frac{2}{9}(-2 + \sqrt{5})x_1 \\ -108x_1 \begin{pmatrix} 5(-12 + 5\sqrt{5})x_1^4 + 18(-25 + 8\sqrt{5})x_1^2x_2 \\ +27(20 + 11\sqrt{5})x_2^2 - \sqrt{5}x_3 \end{pmatrix} & -8x_1\{(-7 + 3\sqrt{5})x_1^2 + 9(1 + \sqrt{5})x_2\} \end{pmatrix} \end{aligned}$$

Then

$$V_j \vec{u} = A_j \vec{u} \quad (j = 1, 2, 3) \quad (2)$$

is a holonomic system, where  $\vec{u} = \begin{pmatrix} u \\ V_2 u \end{pmatrix}$  in this case. The system (2) is equivalent to

$$\partial_{x_j} \vec{u} = B_j \vec{u} \quad (j = 1, 2, 3) \quad (3)$$

where  $B_1, B_2, B_3$  are  $2 \times 2$  matrices such that each of  $h_0 B_j$  has polynomial entries. The equation  $\partial_{x_3} \vec{u} = B_3 \vec{u}$  is rewritten as a differential equation for  $u$ :

$$\partial_{x_3}^2 u + \frac{\tilde{P}_1(x)}{(x_3 - a_s)h_0} \partial_{x_3} u + \frac{\tilde{P}_2(x)}{(x_3 - a_s)h_0^2} u = 0 \quad (4)$$

where both  $\tilde{P}_1, \tilde{P}_2$  are polynomials of  $x_3$  and

$$a_s = \frac{(-2 + \sqrt{5})x_1^6 + (1089 - 594\sqrt{5})x_1^4x_2 + (7128 - 891\sqrt{5})x_1^2x_2^2 + 729x_2^3}{(-2 + \sqrt{5})x_1^2 + 9x_2}.$$

Now we put  $u = h_0^{p_1} v$  for a constant  $p_1$  and obtain a differential equation for  $v$  from (4). In this case, if  $p_1 = \frac{r_0 - 2}{12}$ , then the equation for  $v$  becomes of the form

$$\partial_{x_3}^2 v + \left\{ (1 - r) \frac{h'_0}{h_0} - \frac{1}{x_3 - a_s} \right\} \partial_{x_3} v + \left\{ \frac{c_0 x_3^2 + c_1 x_3 + c_2}{h_0} - \frac{c_0}{x_3 - a_s} \right\} v = 0, \quad (5)$$

where  $r$  is a constant,  $c_0, c_1, c_2$  are rational functions of  $x_1, x_2$  and  $h'_0 = \partial_{x_3} h_0$ . Equation (5) is regarded as an ordinary differential equation with respect to the variable  $x_3$ .

Since  $h_0 = (x_3 - z_0)(x_3 - z_1)(x_3 - z_2)$ , there are four singular points  $x_3 = z_0, z_1, z_2, a_s$  of (5). By the coordinate transformation  $w = \frac{x_3 - z_0}{z_1 - z_0}$ , the points  $z_0, z_1, z_2$  are transformed to  $0, 1, t = \frac{z_2 - z_0}{z_1 - z_0}$ , respectively. We now put  $\lambda = \frac{a_s - z_0}{z_1 - z_0}$ . Then Equation (5) turns out to be

$$\tilde{v}'' + \left\{ (1 - r) \left( \frac{1}{w} + \frac{1}{w - 1} + \frac{1}{w - t} \right) - \frac{1}{w - \lambda} \right\} \tilde{v}' + \left( \frac{A}{w} + \frac{B}{w - 1} + \frac{C}{w - t} + \frac{D}{w - \lambda} \right) \tilde{v} = 0, \quad (6)$$

where  $\tilde{v}$  is a function of  $w$ ,  $\tilde{v}' = \frac{d}{dw} \tilde{v}$ ,  $\tilde{v}'' = \frac{d^2}{dw^2} \tilde{v}$  and  $A, B, C, D$  are independent of  $w$ . It is underlined here that  $\lambda$  is regarded as a function of  $t$ . This follows from the computation in the previous section.

## 5 Relationship with Hitchin's solution

Since  $\lambda = \frac{a_s - z_0}{z_1 - z_0}$ , we obtain the parametric expression of  $\lambda$ :

$$\lambda = \frac{(-1 + s)^4(1 + s)^2(3 + s)(-1 - 4s + s^2)}{(-3 + 7s - s^2 + s^3)(1 + 2s - 5s^2 - 5s^4 - 2s^5 + s^6 + 8s^2u)}. \quad (7)$$

We now recall the elliptic dihedral solution which is one of algebraic solutions of Painlevé sixth equation given in [1], p.11:

$$t_H = \frac{(s^2 + u)^2(s(s+2) - u)(s(s-2) - u)}{(s^2 - u)^2(s(s+2) + u)(s(s-2) + u)}, \quad y = \frac{(3s-1)(s^2 - 4s - 1)(s^2 + u)(s(s+2) - u)}{(3s^3 + 7s^2 + s + 1)(s^2 - u)(s(s-2) + u)}, \quad (8)$$

where  $(s, u)$  lives on the elliptic curve  $u^2 = s(s^2 + s - 1)$ . Note that this solution is obtained by Hitchin [2]. For our purpose, we rewrite  $t_H$  and  $y$  by using the relation between  $s$  and  $u$ . Then

$$t_H = \frac{1 + 2s - 5s^2 - 5s^4 - 2s^5 + s^6 - 8s^2u}{1 + 2s - 5s^2 - 5s^4 - 2s^5 + s^6 + 8s^2u}, \quad y = \frac{(-1 + 3s)(-1 - 4s + s^2)(1 - s + s^2 + s^3 + 2u)}{(1 + s + 7s^2 + 3s^3)(1 - s - 3s^2 + s^3 + 2u)}. \quad (9)$$

Clearly  $t_H$  coincides with the function  $t$  defined in (1) but  $y$  seems not to equal to the function  $\lambda$  defined in (7). To explain the difference, we first point out the existence of an automorphism  $\chi$  on the elliptic curve  $u^2 = s(s^2 + s - 1)$  defined by  $(s, u) \rightarrow (-\frac{1}{s}, \frac{u}{s^2})$ . By the action of  $\chi$ ,  $t_H$  is fixed but  $y$  turns out to be

$$y_H = \frac{(s+3)(-1-4s+s^2)(-1+s+s^2+s^3+2su)}{(s^3-s^2+7s-3)(s^3+s^2-3s-1+2su)}.$$

By direct computation, we find that  $y_H$  coincides with the function  $\lambda$  of (7). As a consequence,  $(t, \lambda)$  is equivalent to the solution obtained by Hitchin. At last we note that  $\theta = (\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2})$  in this case (cf.[1]).

## References

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